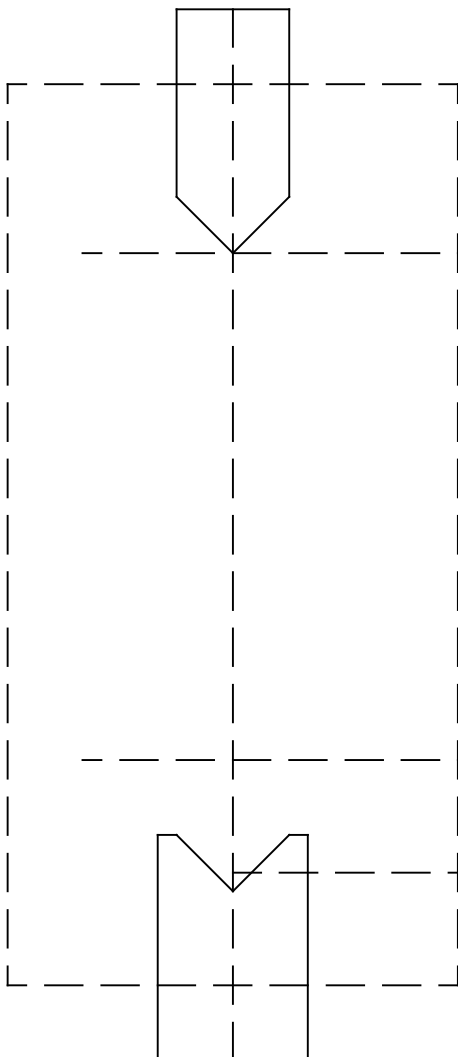


Y Axis



Y 0 (*fixed position*)

Return Position (*adjustable*)

Deceleration Position (*adjustable*)

Down Limit (*adjustable*)

Y -6 (*fixed position*)