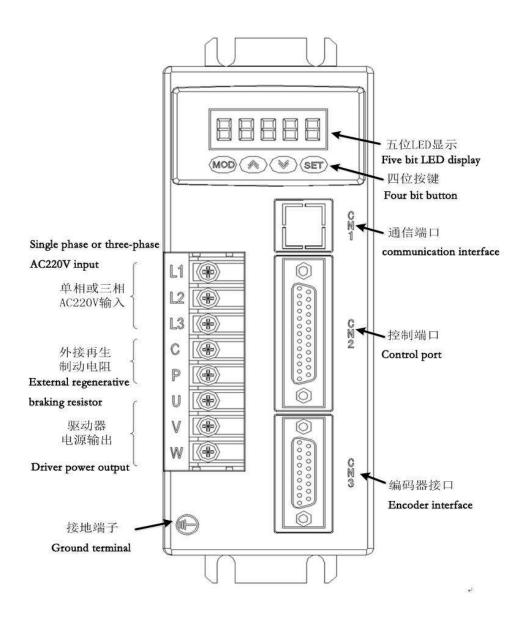
## 1.2 id label



Danger: Please follow the instructions, installation, wiring and use, be sure to reliably grounding

High-voltage power supply: Please don't disassemble the driver during the 5 minutes when the power is on and the power is cut off, so as to prevent electric shock

## 1.3 Product front panel



# 1.4 Drive specification

Input power		① Single phase or three-phase AC220V -15 to +10% 50 / 60Hz					
		② Single phase or three-phase AC380V -15 to +10% 50 / 60Hz					
	temper	Work: store at 0~55 DEG C: -20 ~ 80 DEG C					
environment	ature						
	humid	Less than 90% (without condensation)					
ity							
Vibra		Less than 0.5G (4.9m/S2), 10 to 60Hz (non continuous running)					
	tion						
control mode		IGBT PWM 正弦波控制 power pwm 正弦波控制					
control model		① Torque mode ④Position / speed mode					
		② Speed mode ⑤Position / torque model					
		③ Location mode ⑥Speed / torque mode					
		Servo enable, alarm reset, forward drive, inhibit and reverse drive					
		prohibited, External forward torque limit, external reverse torqu					
		limit, emergency stop, Zero speed clamp, internal speed command					
		select 1, internal speed command select 2Internal speed command					
		select 3, internal torque command select 1, Internal torque command					
		select 2, control mode switching, gain switching, The choice of the					
		electronic gear molecule 1, the electronic gear molecule selection					
		2, the instruction counter, The position deviation is cleared, the					
control in	put	pulse input is forbidden, the proportional control and the origin					
55113151 111	Pat	return trigger, Origin regression reference point, internal					
		position selection 1, internal position selection 2, Trigger an					
		internal position instruction, pause an internal position command,					
		and select an internal and external position commandFixed length,					
		displacement interruption, fixed length unlocking					
Control output		Alarm detection, servo ready, emergency stop detection, positioning					
		completed, Speed arrives, arrives at the predetermined torque, the zero					
Control of	reput	speed examination, the servo motor electrify, Electromagnetic brake, origin					
		return, position approach, torque limit, speed limit, Tracking torque command					
		arrives					
Encoder fee	edback	① 2500 line incremental encoder					
		② 17 bit absolute encoder					
communication mode		① RS-232 ②RS-485					
Display and or	peration	① 5 LED display ②4/5 keys					
Braking m		Energy consumption braking by built-in / external braking resistor					
DI GRITING II							

Cooling method	Air cooling (heat conduction mould, high speed strong cooling fan)
Power range	≤10KW

## 1.5 Servo motor installation

#### Installation environment condition

- Working environment temperature: 0~40 degrees centigrade; working environment temperature: 80% below (without dew).
- Storage environment temperature:  $-40^{\circ}$  50 degrees; storage environment humidity: less than 80% (without condensation).
- Vibration: 0.5G below.
- Well ventilated place with little moisture and dust.
- non corrosive, fire gases, oil and gas, cutting fluid, iron powder and so on.
- no water vapor and direct sunlight.

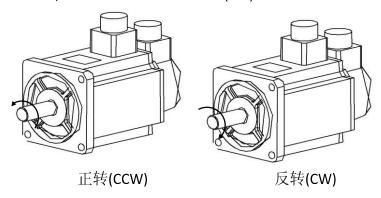
#### Installation method

- horizontal installation: to avoid water, oil and other liquids from the motor outlet end into the motor, please put cable outlet below.
- Vertical mounting: if the motor shaft is mounted upwards and attached to the reducer, attention shall be paid to preventing the grease in the reducer from penetrating into the motor through the motor shaft.
- The extension of the motor shaft needs to be sufficient. If the amount of the extension is insufficient, it will vibrate easily when the motor is moving.

The installation and disassembly of the motor, with a hammer percussion motor do not, otherwise easy to cause damage to the motor shaft and the encoder.

## 1.6 Motor rotation direction

From the motor load side, the motor shaft extends counterclockwise (CCW) for the positive rotation, and the clockwise rotation (CW) is reversed.



## 1.7 Servo unit and motor model adaptation

The 220V drive model and the motor model adaptation sheet are as follows:

Motor model	Pn001	Rated	Rated torque	Rated	KRS	KRS	KRS	KRS	KRS
		speed	(N. M)	power	15	20A	30A	50A	75A
		(r/min)		(KW)					
60st_m00630	0	3000	0.6	0. 2	√	<b>√</b>	√		
60st_m01330	1	3000	1.3	0. 4	√	√	√		
60st_m01930	2	3000	1.9	0.6	√	<b>√</b>	√		
80st_m01330	3	3000	1.3	0. 4	√	√	√		
80st_m02430	4	3000	2. 4	0. 75	√	<b>√</b>	√		
80st_m03520	5	2000	3. 5	0. 73	√	√	√		
80st_m04025	6	2500	4	1	√	√	√		
90st_m02430	7	3000	2. 4	0. 75	√	√	√		
90st_m03520	8	2000	3. 5	0. 73	√	√	√		
90st_m04025	9	2500	4	1	√	√	√		
110st_m02030	10	3000	2	0.6	√	√	<b>√</b>		
110st_m04020	11	2000	4	0.8	√	<b>√</b>	√		
110st_m04030	12	3000	4	1. 2		√	√		